

Advance Information

Bus Controlled Multistandard Video Processor

The Motorola MC44011, a member of the MC44000 Chroma 4 family, is designed to provide RGB or YUV outputs from a variety of inputs. The inputs can be composite video (two inputs), S–VHS, RGB, and color difference (R–Y, B–Y). The composite video can be PAL and/or NTSC as the MC44011 is capable of decoding both systems. Additionally, R–Y and B–Y outputs and inputs are provided for use with a delay line where needed. Sync separators are provided at all video inputs.

In addition, the MC44011 provides a sampling clock output for use by a subsequent triple A/D converter system which digitizes the RGB/YUV outputs. The sampling clock (6.0 to 40 MHz) is phase–locked to the horizontal frequency.

Additional outputs include composite sync, vertical sync, field identification, luma, burst gate, and horizontal frequency.

- Control of the MC44011, and reading of status flags, is via an I2C bus.
- Accepts NTSC and PAL Composite Video, S–VHS, RGB, and R–Y, B–Y
- Includes Luma and Chroma Filters, Luma Delay Lines, and Sound Traps
- Digitally Controlled via I²C Bus
- R–Y, B–Y Inputs for Alternate Signal Source
- Line–Locked Sampling Clock for A/D Converters
- Burst Gate, Composite Sync, Vertical Sync and Field Identification Outputs
- RGB/YUV Outputs can Provide 3.0 Vpp for A/D Inputs
- Overlay Capability
- Single Power Supply: 5.0 V, \pm 5%, 550 mW (Typical)
- 44 Pin PLCC and QFP Packages

BUS CONTROLLED MULTISTANDARD VIDEO PROCESSOR

SEMICONDUCTOR TECHNICAL DATA

ORDERING INFORMATION

MODE and the subject to change without notice. This document contains information on a new product. Specifications and information herein are subject to change without notice.

ELECTRICAL CHARACTERISTICS (The tested electrical characteristics are based on the conditions shown in Table 1 and 2. Composite Video input signal = 1.0 Vpp, composed of: 0.7 Vpp Black–to–White; 0.3 Vpp Sync–to–Black; 0.3 Vpp Color Burst. V_{CC1} = V_{CC2} $=$ V_{CC3} = 5.0 V, I_{ref} = 32 μ A (Pin 9), unless otherwise noted.)

Table 1. Control Bit Test Settings

Table 2. DAC Test Settings

NOTE: Currents out of a pin are designated –, and those into a pin are designated +.

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MAXIMUM RATINGS

NOTES: 1. Devices should not be operated at these limits. The "Recommended Operating Conditions" table provides for actual device operation.

2. ESD data available upon request.

RECOMMENDED OPERATING CONDITIONS

NOTE: All limits are not necessarily functional concurrently.

ELECTRICAL CHARACTERISTICS $(T_A = 25^\circ\text{C}, V_{CC1} = V_{CC2} = V_{CC3} = 5.0 \text{ V}, \text{unless otherwise noted.)}$

ELECTRICAL CHARACTERISTICS (continued) $(T_A = 25^{\circ}C, V_{CC1} = V_{CC2} = V_{CC3} = 5.0 V$, unless otherwise noted.)

NOTE: 1. This spec indicates a correct output amplitude at Pins 41 and 42, with respect to Y1 output. For standard color bar inputs, the output amplitude is between 1.5 and 1.7 Vpp, with the settings in Tables 1 and 2.

ELECTRICAL CHARACTERISTICS (continued) $(T_A = 25^{\circ}C, V_{CC1} = V_{CC2} = V_{CC3} = 5.0 V$, unless otherwise noted.)

ELECTRICAL CHARACTERISTICS (continued) $(T_A = 25^{\circ}C, V_{CC1} = V_{CC2} = V_{CC3} = 5.0 V$, unless otherwise noted.)

ELECTRICAL CHARACTERISTICS (continued) $(T_A = 25^{\circ}C, V_{CC1} = V_{CC2} = V_{CC3} = 5.0 V,$ unless otherwise noted.)

PIN FUNCTION DESCRIPTION

Luma Frequency Response (14.3 MHz) Crystal, (4.5 MHz) Sound Trap

Luma Frequency Response (17.7 MHz) Crystal, (5.5/5.75 MHz) Sound Trap

Luma Frequency Response (17.7 MHz) Crystal, (6.0 MHz) Sound Trap

Luma Frequency Response (17.7 MHz) Crystal, (6.5 MHz) Sound Trap

(4.5 MHz) Sound Trap

(6.0 MHz) Sound Trap

(6.5 MHz) Sound Trap

NOTE: In above waveforms, all timing is referenced to the **center** of the incoming Sync Pulse at Pin 26 to 28, or 29. Above timings based on a 4.6 µs wide sync pulse. Lower two levels of Sandcastle output alternate, based on video system in effect.

Figure 28. System Timing/Video Inputs to RGB Outputs

Figure 33. Vertical Timing (NTSC System)

Figure 34. Vertical Timing (PAL System)

MC44011 FUNCTIONAL DESCRIPTION

Introduction

The MC44011, a member of the MC44000 Chroma 4 family, is a composite video decoder which has been tailored for applications involving multimedia, picture–in–picture, and frame storage (although not limited to those applications). The first stage of the MC44011 provides color difference signals (R–Y, B–Y, and Y) from one of two (selectable) composite video inputs, which are designed to receive PAL, NTSC, and S–VHS (Y,C) signals. The second stage provides either RGB or YUV outputs from the first stage's signals, or from a separate (internally selectable) set of RGB inputs, permitting an overlay function to be performed. Adjustments can be made to saturation; hue; brightness; contrast; brightness balance; contrast balance; U and V bias; subcarrier phase; and color difference gain ratio.

The above mentioned video decoding sections provide the necessary luma/delay function, as well as all necessary filters for sound traps, luma/chroma separation, luma peaking, and subcarrier rejection. External tank circuits and luma delay lines are not needed. For PAL applications, the MC44140 chroma delay line provides the necessary line–by–line corrections to the color difference signals required by that system.

The MC44011 provides a pixel clock to set the sampling rate of external A/D converters. This pixel clock, and other horizontal frequency related output signals, are phase–locked to the incoming sync. The VCO's gain is adjustable for optimum performance. The MC44011 also provides vertical sync and field identification (Field 1, Field 2) outputs.

Selection of the various inputs, outputs, and functions, as well as the adjustments, is done by means of a two–wire I2C interface. The basic procedure requires the microprocessor system to read the internal flags of the MC44011, and then set the internal registers appropriately. This I²C interface eliminates the need for manual controls (potentiometers) and external switches. All of the external components for the MC44011, except for the two crystals, are standard value resistors and capacitors, and can be non–precision.

(The DACs mentioned in the following description are 6–bits wide. The settings mentioned for them are given in decimal values of 00 to 63. These are not hex values.)

PAL/NTSC/S–VHS Decoder

A block diagram of this decoder section is shown in Figure 35. This section's function is to take the incoming composite video (at Pins 1 or 3), separate it into luma and chroma information, determine if the signal is PAL or NTSC (for the flags), and then provide color difference and luma signals at the outputs. If the input is S–VHS, the luma/chroma separation is bypassed, but the other functions are still in effect.

Figure 35. PAL/NTSC/S–VHS Decoder Block Diagram

Inputs

The inputs at Pins 1 and 3 are high impedance inputs designed to accept standard 1.0 Vpp positive video signals (with negative going sync). The inputs are to be capacitor–coupled so as not to upset the internal dc bias. When normal composite video is applied, the desired input is selected by Bit \$88–7. Bits \$77–6 and \$77–7 must be set to 0 so that their switches are as shown in Figure 35. The selected signal passes through the sound trap, and is then separated by the chroma trap and the chroma (high pass) filter.

When S–VHS signals (Y,C) are applied to the two inputs, Bit \$88–7 is used to direct the luma information to the sound trap, and the chroma information to the ACC circuit (Bit \$77–6 must be set to a Logic 1). Bit \$77–7 is normally set to a Logic 1 in this mode to bypass the first luma delay line and the chroma trap, but it can be left 0 if the additional delay is desired.

Sound Trap

The sound trap will filter out any residual sound subcarrier at the frequency selected by control bits T1 and T2 according to Table 3. The accuracy of the notch frequency is directly related to the selected crystal frequency.

Crystal Frequency	Т1 $($7B-7)$	T1 $($7B-6)$	Notch Frequency	
	n	0	6.5 MHz	
17.73 MHZ	O		$5.5 + 5.75$ MHz	
		U	6.0 MHz	
			5.5 MHz	
	n	0	5.25 MHz	
14.32 MHz	n	1	$4.44 + 4.64$ MHz	
		0	4.84 MHz	
			4.44 MHz	

Table 3. Sound Trap Frequency

Code 01 (for T1, T2) is used to widen the band rejection where stereo is in use. Typical rejection is 30 dB.

ACC and PAL/NTSC Decoder

The chroma filter bandpass characteristics (3.58 or 4.43 MHz) is determined by the selected crystal. The output of the chroma filter is sent to the ACC circuit which detects the burst signal, and provides automatic gain control once the crystal oscillator has achieved phase lock–up to the burst. The dc voltage at Pin 2 is \approx 1.5 to 2.0 V. This will occur if the burst amplitude exceeds 30 mVpp, and if the correct crystal is selected (Bit \$7A–7). A 17.734472 MHz crystal is required for PAL, and a 14.31818 MHz crystal is required for NTSC. When Flag 23 is high, it indicates that the crystal's PLL has locked up, and the ACC circuit is active, providing automatic gain control. A small amount of phase adjustment $(\approx \pm 5^{\circ})$ of the crystal PLL, for color correction, can be made with control DAC \$79–5/0. Pin 2 is the filter for the ACC loop, and Pin 44 is the filter for the crystal oscillator PLL.

The PAL/NTSC decoder then determines if the signal is PAL or NTSC by looking for the alternating phase characteristic of the PAL burst. When Flag 24 is high, PAL has been detected. Bits SSA, SSB, SSC, and SSD (Table 4) must then be sent to the decoder to set the appropriate decoding method.

Upon receiving the SSA to SSD bits, the decoder provides the correct color difference signals, and with the Identification circuit, provides the correct level at the System Select output (Pin 34). This output is used by the MC44140 delay line.

The color kill setting $(SSA = SSB = 1)$ should be used when the ACC flag is 0, when the color system cannot be properly determined, or when it is desired to have a black–and–white output (the ACC circuit and flag will still function if the input signal has a burst signal). The "External" setting $(SSC = 1)$ is used when an external (alternate) source of color difference signals are applied to the MC44140 delay line. (See Miscellaneous Applications Information for more details.)

Color Difference Controls and Outputs

The color difference signals (R–Y, B–Y) from the PAL/NTSC decoder are directed to the saturation, hue and color balance controls, and then through a series of notch filters before being output at Pins 41 and 42. Blanking and clamping are applied to these outputs.

The saturation control DAC(\$87–5/0) varies the amplitude of the two signals from 0 Vpp (DAC setting $= 00$), to a maximum of $≈ 1.8$ Vpp (at a DAC setting of 63). The maximum amplitude (without clipping) is \approx 1.5 Vpp, but a nominal setting is \approx 1.3 Vpp at a DAC setting of 15.

The hue control (\$88–5/0) varies the relative amplitude of the two signals to provide a hue adjustment. The nominal setting for this DAC is 32.

The color balance control (\$78–5/0) provides a fine adjustment of the relative amplitude of the two outputs. This provides for a more accurate color setting, particularly when NTSC signals are decoded. The nominal setting for this DAC is 32, and should be adjusted before the hue control is adiusted.

The notch filters provide filtering at the color burst frequency, and at 2x and 8x that frequency. Additionally, blanking and clamping (derived from the horizontal PLL) are applied to the signals at this stage. The nominal output dc level is ≈ 2.0 to 2.5 Vdc, and the load applied to these outputs should be >10 k Ω . Sync is not present on these outputs.

Luma Peaking, Delay Line, and Y1 Output

When composite video is applied, the luma information extracted in the chroma trap is then applied to a stage which allows peaking at ≈ 3.0 MHz with the 17.7 MHz crystal (≈ 2.2 MHz with the 14.3 MHz crystal). The amount of peaking at Y1 is with respect to the gain at the minimum peaking value (P1, P2, P3 = 111), and is adjustable with Bits \$7D–7, and \$7E–7,6 according to Table 5.

The luma delay lines allow for adjustment of that delay so as to correspond to the chroma delay through this section. Table 6 indicates the amount of delay using the D1–D3 bits (\$7F–7,6, and \$80–6). The delay indicated is the total delay from Pin 1 or 3 to the Y1 output at Pin 33. The amount of delay depends on whether Composite Video is applied, or YC signals (S–VHS) are applied.

The output impedance at Y1 is $\approx 300 \Omega$, and the black level clamp is at \approx 1.1 V. Sync is present on this output. Y1 is also internally routed to the color difference stage.

17.7 MHz Crystal, 6.5 MHz Sound Trap, Composite Video Mode

Color Difference Stage and RGB/YUV Outputs

A block diagram of this section is shown in Figure 36. This section's function is to take the color difference input signals (Pins 30, 31), or the RGB inputs (Pins 26 to 28), and output the information at Pins 20 to 22 as either RGB or YUV.

The inputs (on the left side of Figure 36) are analog RGB, or color difference signals (R–Y and B–Y) with Y1 or Y2 as the luma component. Pin 25 (Fast Commutate) is a logic level input, used in conjunction with RGB EN (Bit \$80–7), to select the RGB inputs or the color difference inputs. The outputs (Pins 20 to 22) are either RGB or YUV, selected with Bit \$82–7. The bit numbers adjacent to the various switches and gates indicate the bits used to control those functions. Table 7 indicates the modes of operation.

FC	RGB EN $$80 - 7$	YX EN $$82-6$	YUV EN $$82 - 7$	Function		
	0	Ω	0	RGB inputs, RGB outputs, no saturation control		
	0		0	RGB inputs, RGB outputs, with saturation control		
	0			RGB inputs, YUV outputs, with saturation control		
	0	Ω		Not usable		
FC Low and/or RGB EN Hi		X	Ω	R-Y, B-Y inputs, RGB outputs. Y1 or Y2 must be selected		
FC Low and/or RGB EN Hi		X		R-Y, B-Y inputs, YUV outputs. Y1 or Y2 must be selected		

Table 7. Color Difference Input/Output Selection

In addition to Table 7, the following guidelines apply:

- a. To select the RGB inputs, both FC must be high and RGB EN must be low. Therefore, the RGB inputs can be selected either by the I2C bus by leaving FC permanently high, or by the FC input by leaving Bit \$80–7 permanently low. For overlay functions, where high speed, well controlled switching is necessary, the FC pin must be the controlling input.
- b. When the R–Y, B–Y inputs are selected, either Y1 or Y2 must be selected, and the other must be deselected. The YX input is automatically disabled in this mode.
- c. In applications where the color difference inputs are obtained from the NTSC/PAL decoder (from a composite video signal), Y1 is used. The Y2 input is normally used where alternately sourced color difference signals are applied, either through the MC44140 delay line, or through other external switching to Pins 30 and 31.

In Figure 36, the bit numbers followed by "–0/5" indicate DAC operated controls (contrast, brightness, etc.), which are controlled by the I2C bus. The DACs have 6–bit resolution, allowing 64 adjustment steps. Table 8 provides guidelines on the DAC operation.

Table 8. DAC Operation – Color Difference Section

Figure 36. Color Difference Stage and Outputs

The RGB and Y2 inputs are designed to accept standard 1.0 Vpp analog video signals. They are not designed for TTL level signals. The color difference inputs are designed to accept signals ranging up to 1.8 Vpp. All signals are to be capacitor–coupled as clamping is provided internally. Input impedance at these six pins is high.

For applications involving externally supplied color difference signals, sync can be supplied on the luma input (Y2), or it can be supplied separately at the RGB inputs. Where the color difference signals are obtained from the NTSC/PAL decoder, sync is provided to this section on the internal Y1 signal. See Sync Separator section for more details on injecting sync into the MC44011.

Sync is present on all three outputs in the RGB mode, and on the Y output only (Pin 21) in the YUV mode.

The Fast Commutate input (FC, Pin 25) is a logic level input with a threshold at ≈ 0.5 V. Input impedance is ≈ 67 k Ω , and the graph of Figure 24 shows the input current requirements. Propagation delay from the FC pin to the RGB/YUV outputs is \approx 50 ns when enabling the RGB inputs, and \approx 90 ns when disabling the inputs. (See Figure 29 Fast Commutate Timing diagram.) If Pin 25 is open, that is equivalent to a Logic 1, although good design practices dictate that inputs should never be left open. The voltage on this pin should not be allowed to go more than 0.5 V above V_{CC2} or below ground.

The three outputs (Pins 20 to 22) are open–collector, requiring an external pull–up. A representative schematic is shown in Figure 37.

The output amplitude can be varied from 100 mVpp to 3.0 Vpp by use of the contrast and saturation controls. Any output load to ground should be kept larger than 1.0 kΩ. In the RGB mode, DACs \$7D and \$7E should be set to 00, which results in clamping levels of \approx 1.4 Vdc. In the YUV mode, DACs \$7D and \$7E should be set to 00, which results

Figure 37. Output Stage

in clamping levels of \approx 1.4 Vdc. In the YUV mode, the DACs should be set to 32 to bias the U and V outputs to \approx 2.3 V. The Y output clamp will remain at \approx 1.4 V in the YUV mode.

Horizontal PLL (PLL1)

PLL1 (shown in Figure 38) provides several outputs which are phase–locked to the incoming horizontal sync. In normal operation, the two switches at the left side of Figure 38 are as shown, and (usually) the transistor at Pin 12 is off.

The phase detector compares the incoming sync (from the sync separator) to the frequency from the \div 64 block. The phase detector's output, filtered at Pin 11, controls the VCO to set the correct frequency (\approx 1.0 MHz) so that the output of the \div 64 is equal to the incoming horizontal frequency. The line–locked outputs are:

- 1) **Fh Ref** (Pin 14) A square wave, TTL levels, at the horizontal frequency, and phase–locked to the sync source according to the timing diagram of Figures 25 and 27.
- 2) **Burst Gate** (Pin 8) This is a positive going pulse, TTL levels, coincident with the burst signal. See the timing diagram of Figures 25 and 27.

- 3) **Sandcastle Output** (Pin 35) This is a multilevel output, at the horizontal frequency, used by the MC44140 delay line. See the timing diagram of Figures 25 and 27.
- 4) **16Fh/CSync** (Pin 13) This is a dual purpose output, TTL levels, user selectable. When Bit \$85–6 is set to 0, Pin 13 is a square wave at 16x the horizontal frequency (250 kHz for PAL, \approx 252 kHz for NTSC). When Bit \$85–6 is set to 1, Pin 13 is negative composite sync, derived from the internal sync separator. See the timing diagram of Figures 25 and 27.

The first three outputs mentioned above, and Pin 13 when set to 16Fh, are consistent, and do not change duty cycle or wave shape during the vertical sync interval. These four outputs will also be present regardless of the presence of a video signal at the selected input.

When Pin 13 is set to C_Syn_C output, it follows the incoming composite sync format. If there is no video signal present at the selected input, this output will be a steady logic high.

Loading on these pins should not be less than 2.0 kΩ to either ground or 5.0 V.

Pin 11 is the filter for the PLL, and requires the components shown in Figure 38, and with the values shown in the application circuit of Figure 42. Pin 12 is a switch which allows the filtering characteristics at Pin 11 to be changed. Switching in the additional components (set $$84-7 = 1$) increases the filter time constant, permitting better performance in the presence of noisy signals.

The gain of the phase detector may be set high or low, depending on the jitter content of the incoming horizontal frequency, by using Bit \$83–6. Broadcast signals usually have a very stable horizontal frequency, in which case the low gain setting $(\$83–6 = 0)$ should be used. When the video source is, for example, a VCR, the high gain setting may be preferable to minimize instability artifacts which may show up on the screen.

The gating function (\$77–2) provides additional control where the stability of the incoming horizontal frequency is in question. With this bit set to 0, gating is in effect, causing the phase detector to not respond to the incoming sync pulses during the vertical interval. This reduces disturbances in this PLL due to the half–line pulses and their change in polarity. The gating may be disabled by setting this bit to 1 where the timing of the incoming sync is known to be stable. The gating cannot be enabled if the phase detector gain is set high $($83–6 = 1).$

Calibration Loop

The calibration loop (upper left portion of Figure 38) maintains a near correct frequency of this PLL in the absence of incoming sync signals. This feature minimizes re–adjustment and lock time when sync signals are re–applied. The calibration loop is similar to the PLL function, receiving one frequency from the crystal (either 4.43 MHz or 3.58 MHz) divided down to a frequency similar to the standard horizontal frequency. Bit \$84–6 is used to set the frequency divider to the correct ratio, depending on which crystal is selected (see Table 9). The output of the frequency comparator operates an up/down counter, which in turn sets the D–to–A converter to drive the VCO through switch Sc. The resulting frequency at the output of the divide–by–64 block is then fed to the frequency comparator to complete the loop.

When a sync signal is not present at Phase Detector #1, and at the Coincidence Detector, as indicated by the coincidence detector's output (Flag 12), Bit \$78–6 should be set to 0. This will cause the switch (Sc) to transfer to the D–to–A converter for two lines (lines 4, 5) in each vertical field, and will maintain the PLL1 at a frequency near the standard horizontal frequency (between 14 to 16 kHz). When lock to an incoming sync is established, Bit \$78–6 may be set to 1, disabling the periodic recalibration function, or it may be left set to 0.

If a more accurate horizontal frequency is desired in the absence of an input signal, Bit \$86–6. can be set to 1 (and Bit \$84–6 set according to Table 9). This holds the horizontal frequency to \approx 15.7 kHz. In this mode, Flag 12 will stay 0, as the PLL will not be able to lock–up to a newly applied external signal. To reset the system, set \$86–6 to 0, write \$00 to register \$00, and then check Flag 12 to determine when the loop locks to an incoming signal.

Table 9. Calibration Loop

On initial power up, Bit \$86–6 (PLL1 EN) is automatically set to 1, engaging the calibration loop continuously. This condition will remain until this bit is set to 0, and \$00 is written to register \$00, as part of the initialization routine.

Pixel Clock PLL (PLL2)

The second PLL, depicted in Figure 39, generates a high frequency clock which is phase–locked to the horizontal frequency.

Figure 39. Pixel Clock PLL (PLL2)

The phase and frequency comparator receive inputs from PLL1 (f_H , the horizontal frequency), and the frequency returned from the external divider. Any difference between these two signals causes the Up or Down output to change the charge pump's timing. The charge pump output is composed of two equal current sources which alternately source and sink current to the filter at Pin 16. The voltage at Pin 16 (which is the input to the VCO) is therefore determined by the relative timing of those two current sources, and the filter characteristics. A coarse control of the loop gain is set with Bit \$83–7. Low gain is obtained by setting this bit to a 1, which sets the charge pump's output current sources to ≈ ±20 µA. Setting this bit to 0 sets the current sources to $\approx \pm 50$ µA, or high gain.

Depending on the output frequency desired, and whether or not a 50–50 square wave is needed at the pixel clock, the \div 2 may be engaged (Bit \$85–7). Generally, the \div 2 should not be engaged for high frequencies, and should be engaged for low frequencies, so as to keep the VCO's input voltage in a comfortable range (between 1.7 and 3.3 V). If the input voltage is outside this range, Flag 19 or 20 will switch high, indicating the need to fine tune the VCO's gain (control DAC $$7F$). The usable adjustment range for this DAC is 00 to \approx 50. Settings of 51 to 62 will generally produce non–square wave outputs, and can be unstable. A setting of 63 will shut off the VCO, which should be done if the pixel clock is not used. When not used, Pin 18 will be at a constant low level.

The pixel clock frequency is equal to the horizontal frequency (f_H) x the frequency divider ratio. The frequency divider can be made up of programmable counters (e.g., MC74F161A Applications Information), or it can be integrated into another device (e.g., an ASIC). The returned signal to Pin 15 must be TTL/CMOS logic levels, and must have a low time of > 200 ns. The phase comparator will phase–lock the falling edge of the returned signal with the rising edge of the f_H signal at Pin 14 (see Figure 32).

Vertical Decoder

The vertical decoder section, depicted in Figure 40, provides a vertical sync pulse and a field identification signal, as well as flags which indicate if vertical lockup has occurred, and if the number of horizontal lines per frame is greater or less than 576.

Inputs to this section consists of the composite sync from the sync separator, and horizontal related signals from the horizontal PLL (PLL1).

Figure 40. Vertical Decoder

The sync output (Pin 4) is an active low signal which starts after the horizontal half–line sync pulses change polarity (see Figures 33 and 34). The pulse width is nominally 500 μ s for both PAL and NTSC signals. The position of this sync pulse's leading edge can be altered slightly with Bit \$78–7, but this does not change the pulse width. Since the pulse width is generated digitally by counters, it will not vary with temperature, supply voltage, or manufacturing distribution. The sync output is an open–collector NPN output, requiring an external pull–up resistor. Minimum value for the pull–up is 1.0 kΩ, with 10 kΩ recommended for most applications.

Flag 14 (< 576 lines) is derived from the counter which compares the number of horizontal lines in each frame with a preset value of 576. This flag can be used externally to help determine whether PAL or NTSC signals are being provided to the MC44011. Flag 15 (Vertical countdown engaged) indicates that the vertical decoder has locked–up to the incoming composite sync information for eight consecutive fields $(CB1, CA1 = 11)$.

The operation of the vertical decoder is controlled by Bits \$77–0 and \$77–1, according to Table 10.

Table 10. Vertical Decoder Mode

CB1 (\$77-1)	CA1 (\$77-0)	Vertical Sync Mode	
		Force 625	
		Force 525	
		Injection Lock	
		Auto-Count	

The Injection Lock mode has a quicker response time, but less noise immunity, than the Auto–Count mode, and is normally used when attempting to lock–up to a new signal (such as when changing video input selection). Flag 15 will not switch high when in this mode. The Auto–Count mode, having a higher noise immunity, should be set once the horizontal PLL is locked–up (by reading Flag 12), and then Flag 15 should be checked after 8 fields for vertical lock–up.

The modes designated Force 525 and Force 625 can be used for those cases where it is desired to force the vertical sync pulse to occur twice every 525 or 625 lines, regardless of the incoming signal. In either of these modes, the MC44011's vertical section will not lock–up to the vertical sync information contained in the incoming composite video signal. If there is no incoming video signal, the vertical sync will still occur every 525 or 625 lines generated by the horizontal PLL. Flag 14 will indicate the number of lines selected, and Flag 15 will be a steady high.

Bit \$77–5 (FSI) is used only in the PAL mode to select the vertical sync output rate. With this bit set to 0, the vertical sync pulses will be synchronized with the composite vertical sync input (every 20 ms). With this bit set to 1, the MC44011 will add a second vertical output sync pulse 10 ms after the one occurring at the vertical interval, giving a vertical sync rate of 100 Hz.

The Field ID output (Pin 7) indicates which field is being processed when interlaced signals are applied, but the polarity depends on Bit \$78–7. Table 11 indicates Pin 7 output. When non–interlaced signals are being processed, Pin 7 will be a constant high level when \$78–7 is set to 1, and will be a constant low level when \$78–7 is set to a 0. Loading on Pin 7 should not be less than 2.0 kΩ to either ground or 5.0 V. Figures 33 and 34 indicate the timing.

Table 11. Field ID Output

Sync Separator

The sync separator block provides composite sync information to the horizontal PLL, and to various other blocks within the MC44011 from one of several sources. It also provides composite sync output at Pin 13 when Bit \$85–6 = 1. The sync source is selectable via the I²C bus according to Table 12.

I2C Interface

Communication to and from the MC44011 follows the I2C interface arrangement and protocol defined by Philips Corporation. In simple terms, I2C is a two line, multimaster bidirectional bus for data transfer. See Appendix C for a description of the I²C requirements and operation. Although an I2C system can be multimaster, the MC44011 never functions as a master.

Table 12. Sync Source

Setting Bit \$86–7 to a 1 overrides the other bits, thereby deriving the sync from the composite video input (either Pin 1 or 3) selected by Bit \$88–7.

When RGB is selected, sync information on Pins 26 to 28 is used. Sync may be applied to all three inputs, or to any one with the other two ac grounded. If RGB signals are applied to these pins, sync may be present on any one or all three.

When Y2 is selected, sync information on Pin 29 is used. The sync amplitude applied to any of the above pins must be greater than 100 mV, and it must be capacitor coupled.

This system allows a certain amount of flexibility in using the MC44011, in that if the sync information is not present as part of the applied video signals, sync may be applied to another input. In other words, the input selected for the sync information need not be the same as the input selected for the video information.

SOFTWARE CONTROL OF THE MC44011

The MC44011 has a write address of \$8A, and a flag read address of \$8B. It requires that an external microprocessor read the internal flags, and then set the appropriate registers. The MC44011 does not do any automatic internal switching when applied video signals are changed. A block diagram of the I2C interface is shown in Figure 41. Since writing to the MC44011's registers can momentarily create jitter and other undesirable artifacts on the screen, writing should be done only during vertical retrace (before line 20). Reading of flags, however, can be done anytime.

Figure 41. I2C Bus Interface and Decoder

Write to Control Registers

Writing should be done only during vertical retrace. A write cycle consists of three bytes (with three acknowledge bits):

- 1) The first byte is always the write address for the MC44011 (\$8A).
- 2) The second byte defines the sub–address register (within the MC44011) to be operated on (\$77 through \$88, and \$00).
- 3) The third byte is the data for that register.

Communication begins when a start bit (data taken low while clock is high), initiated by the master, is detected, generating an internal reset. The first byte is then entered, and if the address is correct (\$8A), an acknowledge is generated by the MC44011, which tells the master to continue the communication. The second byte is then entered, followed by an acknowledge. The third byte is the operative data which is directed to the designated register, followed by a third acknowledge.

Sub–Address Registers

The sub–addresses of the 19 registers are at \$77 through \$88, and \$00. Fourteen of the registers use Bits 0–5 to operate DACs which provide the analog adjustments. Most of the other bits are used to set/reset functions, and to select appropriate inputs/outputs. Table 13 indicates the assignments of the registers.

Table 13. Sub–Address Register Assignments

$Sub-$								
Address	$\overline{7}$	6	5	4	3	$\overline{2}$	1	$\bf{0}$
\$77	S-VHSY	S-VHS C	FSI	L ₂ GATE	BLCP	L1 GATE	CBI	CAI
\$78	$36/38$ μ s	Cal Kill	(R-Y)/(B-Y) adjust DAC					
\$79	H _{II}	VI	Subcarrier balance DAC					
\$7A	Xtal	SSD						
\$7B	T1	T ₂						
\$7C	SSC	SSA						
\$7D	P ₁	SSB		Blue bias for YUV operation DAC				
\$7E	P ₃	P ₂		Red bias for YUV operation DAC				
\$7F	D ₃	D ₁		Pixel Clock VCO Gain adjust DAC				
\$80	RGB EN	D ₂		Blue Contrast trim DAC				
\$81	Y ₂ EN	Y1 EN		Main Contrast DAC				
\$82	YUV EN	YX EN	Red Contrast trim DAC					
\$83	L ₂ Gain	L1 Gain		Blue Brightness trim DAC				
\$84	H Switch	525/625		Main Brightness DAC				
\$85	PCIk/2	C Sync	Red Brightness trim DAC					
\$86	V _{in} Sync	PLL1 En	Main Saturation DAC (Color Difference section)					
\$87	Y ₂ Sync	$\mathbf 0$	(R-Y)/(B-Y) Saturation balance DAC (Decoder section)					
\$88	V2/V1	RGB Sync	Hue DAC					
\$00	Set to \$00 to start Horizontal Loop if $$88-6=0$							

Table 14 is a brief explanation of the individual control bits. A more detailed explanation of the functions is found in the block diagram description of the text (within the Functional Description section). Table 15 provides an explanation of the DACs. Each DAC is 6 bits wide, allowing 64 adjustment steps. The proper sequence and control of the bits and DACs, to achieve various system functions, is described in the Applications Information section.

Table 14. Control Bit Description

Table 14. Control Bit Description (continued)

Table 15. Control DAC Description

NOTE: The above DACs are 6–bits wide. The settings mentioned above, and in subsequent paragraphs are given in decimal values of 00 to 63. These are not hex values.

Reading Flags

A read cycle need not be restricted to the vertical interval, but may be done anytime. A flag read cycle consists of three bytes (with three acknowledge bits):

- The first byte is always the Read address for the MC44011 (\$8B).
- The second and third bytes are the flag data.

Communication begins when a start bit (data taken low while clock is high), initiated by the master (not the MC44011), is detected, generating an internal reset. The first byte (address) is then entered, and if correct, an acknowledge is generated by the MC44011. The flag bits will then exit the MC44011 as two 8 bit bytes at clock cycles 10–17 and 19–26. The master (receiving the data) is expected to generate the acknowledge bits at clocks 18 and 27. The master must then generate the stop bit.

The MC44011 flags must be read on a regular basis to determine the status of the various circuit blocks. The MC44011 does not generate interrupts. It is recommended the flags be read once per field or frame. See Table 16 for a description of the flags.

Table 16. Flag Description

MC44011 APPLICATIONS INFORMATION

Design Procedure and PC Board Layout

The external components required by the MC44011 are shown in Figure 42. Except for the crystals, all the components are standard value resistors and capacitors, and can be non–precision. Table 18 describes the external components for each pin.

Figure 42. Basic Functional Circuit

Crystal Specifications and Operation

The crystals used with the MC44011 should comply with Table 17 specifications.

Table 17. Crystal Specifications

The oscillator output resistance at Pin 36 is nominally 300 Ω for NTSC mode, and 400 Ω at Pin 38 for PAL mode. It is recommended that a stray capacitance (PC board, package pins, etc.) of 4.0 to 5.0 pF be included when selecting a crystal.

The above values for tolerance and temperature coefficent can be increased if a trimmer capacitor is used for the load capacitor.

The crystal PLL filter (Pin 44) voltage is between 1.8 and 3.8 V in normal operation. If the color output of the MC44011 is incorrect, or non–existent (ACC flag off), this voltage should be checked. If it is beyond either of the above limits, the capacitor in series with the crystal should be changed so as to allow the PLL to pull–in the crystal. The capacitor is generally specified by the crystal manufacturer, but should also comply with Table 17 specifications. If no burst is present, Pin 44 voltage will be \approx 1.3 V.

The selected crystal frequency can be checked by using a scope at the non–selected crystal pin. The signal amplitude is nominally 200 to 400 mVpp. In this way the selected crystal's frequency is not affected by the scope probe.

Table 18. External Components

Power Supplies and Ground

There are three VCC pins (Pins 19, 23, and 40) which must be connected to a source of 5.0 V, \pm 5%. Since the three pins are internally connected by diodes, none can be left open, even if a particular section (such as the Pixel Clock Generator) is to be unused. Total current required is ≈ 135 mA (including the RGB output load current). There are four ground pins (Pins 10, 17, 24, and 39) which must be connected together, and preferably connected to a ground plane.

Pins 19 and 17 are the V_{CC} and ground for the Pixel Clock Generator, and the circuitry associated with the Pixel Clock should be referenced to those two pins.

Pins 23 and 24 are the V_{CC} and ground for the Color Difference section, which includes the RGB outputs. The output pull-up resistors should be connected to the V_{CC} at Pin 23.

Pins 40 and 39 are the V_{CC} and ground for the Color Decoder, Sync Separator, Horizontal PLL and the Vertical Decoder. Pin 10 is the Quiet Ground for the horizontal PLL's VCO and filter, and therefore, the components on Pins 9 and 11 should be connected as close as possible to Pin 10.

Bypassing of the power supplies must be done as close as possible to each V_{CC} pin, and at the output pull-up resistors. Recommended bypassing components are a 10 µF tantalum capacitor in parallel with a 0.01 µF ceramic.

Input Signals

The various video inputs, Video 1 and 2, Red In, Green In, Blue In, R–Y, B–Y, and Y2 inputs, are designed to accept standard level analog video waveforms. They are not designed for digital signals. The input impedance of the above pins is high. The need for 75 Ω terminations for those video signals depends on the video source itself. All of the above signals must be capacitor–coupled as clamping is provided internally.

The I2C inputs (SCL, SDL) are designed according to the I²C specifications, which define V_{OL} as between 0 and 1.5 V, and VOH as between 3.0 V to VCC . See Appendix C.

The 15 k Return and Fast Commutate (Pins 15 and 25, respectively) are designed for TTL level signals. If unused, they should not be left open, but connected to 5.0 V, or ground, as appropriate.

Output Signals

The RGB/YUV outputs are open–collector, and require pull–up resistors (typically 390 Ω) to a clean 5.0 V (V_{CC2}). The output impedance is such that the load impedance (to ground) should be >1.5 kΩ. If it is desired to drive a 75 Ω load (e.g., a monitor) from these outputs, a simple buffer (see Figure 43) can be added.

The Y1 output (Pin 33) has an output impedance of \approx 300 Ω , and can be used as a monitoring point, or to drive the input of the MC44145 sync separator, or other high impedance loads (minimum load for Y1 is 1.0 kΩ). If it is to be used to drive a 75 Ω load, the buffer shown in Figure 43 can be used, except the 390 Ω resistor must be deleted.

The Vertical Sync output (Pin 4) is an open–collector logic level output, and requires a pull–up resistor to 5.0 V. 10 k Ω is recommended, but it can be as low as 1.0 kΩ. The I²C data line (SDL, Pin 6) is also open–collector when it is an output, and can sink a maximum of 3.0 mA. Only one pull–up resistor is required on the SDL line (regardless of the number of devices on that line), and it is typically near the master device. The Field ID, Burst Gate, 16Fh/C_{Sync}, Fh Ref, and Pixel Clock outputs are logic level totem–pole outputs.

PC Board

The PC board layout should be neat and compact, and should preferably have a ground plane. If feasible, a second plane should be provided for the 5.0 V supply, but this is not mandatory. The components at Pins 9 and 11 should be connected to the same ground track which goes to Pin 10. The V_{CC} and ground should be connected as directly as possible to the power supply, and not routed through a maze of digital circuitry before arriving at the MC44011. Since the MC44011 is intended to be used with A/D converters and high speed digital signals, it is expected digital circuitry will be on the same board. Care should be taken in the layout to prevent digital noise from entering the analog portions of the MC44011. The most sensitive pins are Pins 1, 2, 3, 9, 10, 11, 12, 16, and 44, and should be protected from noise.

Initialization and Programming Information

Upon powering up the MC44011, initialization consists of first filling the registers with initial values to set a known condition. Table 19 provides recommended values for the initial settings, although these may be tailored for each application (with the exception of Bits \$79–6,7, \$7A–6, \$86–6, and \$87–6). Table 19 settings will set up the MC44011 to the following conditions:

- Composite video input at Video 1 (Pin 1), NTSC, using the crystal at Xtal 2 (Pin 36).
- Y1 enabled, RGB outputs enabled, and Composite Sync at Pin 13
- RGB inputs not enabled (R–Y, B–Y inputs are enabled)
- The Sound Trap at 4.5 MHz
- The Luma Peaking at 0 dB
- The Luma Delay at minimum
- High gain and high noise rejection for the horizontal PLL
- Vertical decoder set to Injection Lock mode
- The Pixel Clock VCO is off

After the registers are initialized, then set Bit \$86–6 to 0, and load register \$00 with \$00. This will enable the horizontal PLL, permitting normal operation.

Table 19. Recommended Initial Settings

$Sub-$ Address	7	6	5	4	3	$\mathbf{2}$	1	0	
\$77	$S-VHS$ $Y = 0$	$S-VHS C = 0$	$FSI = 0$	L ₂ Gain = 0	$BLCP = 0$	L1 Gain = 0	$CBI = 0$	$CAI = 1$	
\$78	$36/68 \,\mu s = 0$	$Calkill = 0$		$(R-Y)/(B-Y)$ Adjust DAC = 32					
\$79	$Hl = 1$	$VI = 1$		Subcarrier Balance DAC = 32					
\$7A	$Xtal = 1$	$SSD = 0$	\equiv						
\$7B	$T1 = 1$	$T2 = 1$	-						
\$7C	$SSC = 0$	$SSA = 1$	$\overline{}$						
\$7D	$P1 = 1$	$SSB = 0$	Blue Bias = 00						
\$7E	$P3 = 1$	$P2 = 1$		$Red Bias = 00$					
\$7F	$D3 = 0$	$D1 = 0$		Pixel Clock VCO Gain Adjust = 63					
\$80	$RGB EN = 1$	$D2 = 0$	Blue Contrast Trim $=$ 32						
\$81	$Y2 EN = 0$	$Y1 EN = 1$	Main Contrast = 47						
\$82	YUV $EN = 0$	$YX EN = 0$	Red Contrast Trim = 32						
\$83	L ₂ Gain = 1	L1 Gain = 1	Blue Brightness Trim = 32						
\$84	H Switch = 1	$525/625 = 1$	Main Brightness = 30						
\$85	$PClk/2 = 1$	$C_{\text{sync}} = 1$	Red Brightness Trim = 32						
\$86	V_{in} Sync = 1	PLL1 $EN = 1$	Main Saturation (Color Difference section) = 32						
\$87	$Y2$ Sync = 0	$\mathbf 0$	(R-Y)/(B-Y) Saturation Balance (Decoder section) = 15						
\$88	$V2/V1 = 1$	$RGBSync = 0$	$Hue = 32$						

NOTE: These settings are for power–up initialization only. Refer to the text, and Appendix B, for subsequent modifications based on the application.

Then, after selecting the desired input(s) (from Pins 1, 3, or 26 to 31), and based on the applied signals at those inputs, and by reading the flags, the registers are adjusted for the desired and proper mode of operation. A suggested routine for setting modes is given in Appendix B. The "initial values" in the Control DACs table of Appendix B are those in Table 19. The remainder of the flow chart is a recommendation only, and should be tailored for each application.

The monitoring of flags should be done on a regular basis, and it is recommended it be done once per field. See Table 16 (in the Functional Description section) for a summary of the flags. Should any flags change, the following procedures are recommended:

Flag 11 (Horizontal Enabled) – Once enabled by setting Bit $$86-6 = 0$, this flag should always remain a 1. Should it change to 0, reset \$86–6 to 0, and write \$00 to register \$00 again. If the flag does not return to a 1, this indicates a possible device malfunction.

Flag 12 (Horizontal Out–of–Lock) – When 1, this indicates:

- a. the wrong input is selected (Bits \$88–7, \$81–7, \$80–7, and \$77–7,6), or;
- b. the wrong sync source is selected (Bits \$86–7, \$87–7, and \$88–6), or;
- c. the incoming signal is somewhat unstable, as from a VCR tape (change Bit \$83–6), and/or;
- d. the incoming signal is noisy (change Bit \$84–7), or;
- e. a loss of the incoming signal with sync.

(It is possible for this flag to flicker when the video signal is from a poor quality tape, or other poor quality source.)

Flag 14 (Less than 576 lines) – This flag, from the vertical decoder, is used to help determine if the signal is PAL or NTSC. Should it change, this indicates the incoming signal has changed format, or possibly one of the items listed under Flag 12 above.

Flag 15 (Vertical Countdown Engaged) – Bits 77–0 and 1 must be set to 1 (after Flag 12 reads 0) for this flag to indicate correctly. Then this flag will change to a 1 after 8 fields of successful synchronization of the internal counters with the incoming signal. To change to a 0 requires 8 consecutive fields of non–synchronization. If this flag changes to 0, this indicates a loss of signal, a change of signal format, or instability in the horizontal PLL.

Flags 19, 20 (VCO Control Voltage Low/High) – These flags are meaningful only if the Pixel Clock Generator is used. If Flag 19 is a 1, the gain of the pixel clock VCO needs to be increased by increasing the value of register \$7F, and/or set Bit $$85-7 = 1$. If Flag 20 is a 1, the value of the register must be decreased, and/or set Bit $$85-7 = 0$. If the VCO is turned off ($$7F = 63$), Flag 19 will be 0, and Flag 20 will be 1.

Flag 23 (ACC Active) – If this flag is a 0, it indicates the ACC loop is not active. This will happen if the burst signal is less than 30 mVpp, if the incorrect crystal is selected (\$7A–7), if the crystal PLL is not locked, or if the horizontal PLL is not locked.

Flag 24 (PAL Identified) – This flag is a 1 when PAL signals are applied, and a 0 when NTSC signals are applied, or when no burst is present.

It is recommended that the Color Decoder section, and crystal, should be set according to the state of Flags 14, 23, and 24 according to Table 20.

Table 20. Color Standard Selection Table

	Flags		Bit Settings					
#14 <576 Lines	#23 ACC Active	#24 PAL Signal	Crystal	SSA $($7C-6)$	SSB $($7D-6)$	SSC $($7C-7)$	System	
X		х	Either			Ω	Color Kill	
			Either			0	Color Kill	
Ω			17.7 MHz	Ω		0	PAL	
		0	14.3 MHz			0	NTSC	
			(Note 1)	0		Ω	PAL-M	

NOTES: 1. PAL–M, used in Brazil and other South American countries, can be decoded by the MC44011, but requires a 14.3024 MHz crystal. 2. SSD (\$7A–6) is always set to 0.

MISCELLANEOUS APPLICATIONS INFORMATION

Use of the MC44140 Delay Line

The MC44140 delay line is generally required if PAL signals are to be decoded, so as to average out the line–by–line color information associated with PAL color decoding. If the same single PAL video source is always used in a particular application, the delay line can be eliminated, and any slight phase errors can be corrected with the DAC of register \$79–5/0. If, however, various video sources can be used, and/or if the video signal is less than broadcast quality, it is recommended the MC44140 delay line be included.

The MC44140 acts on the color difference signals before they enter the color difference stage of the MC44011. It will, however, pass NTSC signals through without modifications. The MC44011 uses the System Select output (Pin 34) to indicate to the delay line which signals are being processed. The System Select voltage is set when the color decoder is set with Bits SSA, SSB, SSC, SSD. The Sandcastle output (Pin 35) provides the horizontal timing signals to the delay line. In addition, the MC44140 uses the crystal frequency for the internal counters.

The MC44140 is inserted into the circuit between the Color Difference outputs and inputs of the MC44011. In addition, the MC44140 provides pins (Pins 8,9) for inserting an alternate source of color difference signals to the MC44011 by setting the System Select to external (Bit \$7C–7 = 1). See Figure 44 for a suggested circuit.

If only NTSC signals are to be processed by the MC44011, the MC44140 is not needed. In this case, connect Pin 42 to Pin 31 with a 0.1 µF capacitor, and similarly connect Pin 41 to Pin 30.

Figure 44. Incorporating the MC44140 Delay Line

Figure 45. Typical Waveforms

Use of the MC44145 Pixel Clock Generator

For most applications the Pixel Clock Generator (PLL2) within the MC44011 will be suitable. In those cases, however, where the pixel clock frequency is set to within ±1.0 MHz of the selected crystal frequency (14.3 MHz or 17.7 MHz), or to within \pm 1.0 MHz of double the selected crystal frequencies, undesirable noise artifacts may be present on the RGB outputs. In these cases the MC44145 should be used to generate the Pixel Clock. The circuitry within the MC44145 duplicates that of the MC44011, but since it is physically removed from the circuitry within the MC44011, the interfering noise is not generated. If the MC44145 is used, the Pixel Clock Generator within the MC44011 should be shut off by setting the DAC of register \$7F to 63, eliminating the components at Pin 16, and grounding Pin 16.

If the desired pixel clock frequency is close to the limits mentioned above, then experimentation may be used to determine the need for the MC44145.

Frequency Divider

The frequency of the Pixel Clock is determined by the horizontal frequency and an external frequency divider. The divider simply divides down the Pixel Clock Frequency so that it equals the horizontal frequency. The PLL within the MC44011 (or the MC44145) compares the horizontal frequency with the returned frequency, and adjusts the internal VCO accordingly, to achieve the proper relationship between the two. The PLL will phase–lock the negative–going edge of the returned signal with the positive–going edge of the Fh signal (Pin 14 of the MC44011). The returned signal must be TTL logic level amplitudes, and have a minimum low time of 200 ns. A suggested circuit for the divider, shown in Figure 46, uses 74F161 programmable binary counters. The 12 switches at the bottom are used to set the division ratio, and hence the Pixel Clock frequency.

The division ratio is determined by dividing the desired clock frequency by the horizontal frequency, and then using the closest whole number. After determining the binary equivalent of that number, close each switch corresponding to a 1, and leave open each switch corresponding to a 0. Alternately, the switches could be deleted, and Pins 3, 4, 5 and 6 of each 74F161 hard–wired to 5.0 V or ground, or controlled by a microprocessor where different pixel clock frequencies are required.

Figure 46. Suggested Frequency Divider

Connecting the MC44011 to the MC44250 or MC44251 A/D Converter

The MC44250 and MC44251 triple A/D converters are designed to accept RGB or YUV inputs, and provide 8–bit equivalents of each. Additionally, the inputs have black level clamps, allowing the input signals to be capacitor–coupled. The simplified schematic of Figure 47 shows the connections between the MC44011 and the MC44250/1, including anti–aliasing filters between the devices. Connection to other A/D converters would be done in a similar manner. Refer to the appropriate data sheet for details.

Figure 47. Connecting to a Triple A/D Converter

Connecting the MC44011 to the MC141621 or MC141625 NTSC Comb Filter

A comb filter can be used ahead of the MC44011 to enhance picture quality by providing a more accurate separation of the luma and chroma components from the composite video, without sacrificing bandwidth. The usual benefits are reduced dot crawl, and increased color purity. Figure 48 (a simplified schematic) shows the normal mode of implementing the MC141621 (NTSC) or MC141625 (PAL/NTSC) comb filter with the MC44011. The two comb filters can also provide the Y and C signals in digital format. Refer to their data sheets for details. The MC14576A operational amplifiers have an internally set gain of 2.

Figure 48. Implementing the Comb Filter

MC44011 APPENDIX A

Control Bit Summary

Control DACs

Flags

MC44011 APPENDIX B

Suggested Mode Setting Routine (Simplified)

MC44011 APPENDIX C

I2C Description

Introduction

The I²C system, a patented and proprietary system developed by Philips Corporation, defines a two–wire communication system. The number of devices in a system is limited only by the system capacitance and data rate. Each device is assigned two unique addresses – one for writing to it, and one for reading from it. Any device may act as a master by initiating a data transfer with any other device (the slave). Data transfer is in 8–bit bytes, and can be in either direction, but not in both directions in one data transfer operation.

Hardware Aspects

The system bus consists of two wires, Clock and Data. All devices must have open–collector (or open–drain) outputs. A single pull–up resistor is required on each line, as shown in Figure C1.

Devices such as the MC44011, which never act as a master, need not have the output drive transistor at the Clock pin. Nominal value for R1 and R2 is 10 kΩ, but can be different to account for system capacitance at high data rates. VR is a switching threshold for input signals.

The significant electrical characteristics are as follows:

- Maximum data rate (Clock frequency) is 100 kHz;
- $-VOL$ max is 0.4 V when sinking 3.0 mA;
- $-V$ _{IL} max is 0.3 x Vp, but at least 1.5 V;
- $-V_{IH}$ min is 3.0 V for a 5.0 V system, or 0.7 x Vp for other supply voltages.
- The maximum input current at Clock and Data at VOL max (when they are inputs) is -10μ A;
- The maximum input current at Clock and Data at 0.9 x Vp (when they are inputs) is 10 µA;
- The maximum pin capacitance is 10 pF;
- Maximum bus capacitance is 400 pF.

Data Transfer

Prior to initiating a data transfer, both lines must be high (all drive transistors off). A device which initiates a data transfer assumes the role of the master, and generates a START condition by taking the Data line low while Clock is still high. At this time, all other devices become listeners. The master will supply the clock for the entire sequence.

The master then sends the 8–bit address by operating both the clock and data lines. Data must be stable during the clock's high time, and can change during the clock's low time. The MSB is sent first. The address must end in a 0 if it is a Write operation (data transfer from master–to–slave), and it must end in a 1 if it is a Read operation.

At the 9th Clock Pulse, the master must release the Data line high, and the slave must provide an acknowledge bit by pulling Data low during this clock time. If the master does not receive a proper acknowledge, it can terminate the operation.

After the first acknowledge, the role of the two devices depends on whether it is a Write or a Read operation, but the master always supplies the clock.

- In a Write operation the master is the transmitter, and the slave is the receiver.
- In a Read operation the slave is the transmitter, and the master is the receiver.

The transmitter then sends the next 8–bit byte. At the 18th Clock Pulse (and every 9th clock pulse thereafter), the transmitter releases the Data line, and the receiver acknowledges by pulling Data low. There is no limit to how many bytes may be sent after the address.

When all data is transferred, the Data line must be released by the transmitter so that the master can set the STOP condition. This is done by first pulling Data low (during clock low), then releasing Data high while clock is high. After this, the bus is free for any other device to initiate a new data transfer.

Definitions

Master – The device which initiates a data transfer (regardless of the data direction), generates the clock, and terminates the transfer.

Slave – The device addressed by the master.

Transmitter – The device which supplies data to the bus.

Receiver – The device which receives data from the bus.

Notice that the master is not necessarily the transmitter, and the slave is not necessarily the receiver.

Other

For additional information on the $12C$ bus specifications; modes of operation; arbitration; and synchronization, contact Philips Corporation.

MC44011 APPENDIX D

PLL Loop Theory

High Frequency Line–Locked Clock Generator

This section is not intended as a complete loop theory, its aim is merely to point out the idiosyncrasies of the loop, and provide the user with enough information for the selection of filter components. For a more in depth explanation, the references at the end of this section may be consulted.

The following general remarks apply to the loop (PLL2): – The loop frequency is \approx 15.7 kHz.

- In spite of the samples nature of the loop, a continuous time approximation is possible if the loop bandwidth is sufficiently small.
- Ripple on V_{C} (filter pin) is a function of loop bandwidth.
- The loop is a type II, 3rd order. However, since C2 is small, the pole it creates is far removed from the low frequency dominant poles, and the loop can be analyzed as a 2nd order loop.

The following remarks apply to the Phase and Frequency Comparator:

- Phase and frequency sensitive.
- Independent of duty cycle.
- It has 3 allowed states: up, down, and off (high impedance).
- The VCO is always pulled in the right direction during acquisition.
- The Comparator's gain is higher at or near lock.

The last two remarks imply that only the higher value need be taken into account, as acquisition will be slower but always in the correct direction, whereas the higher gain will come into action as soon as the error reaches 2π.

The following values are selected and defined:

 $C2 = C1/10$ or less, to satisfy the requirement that the effect of C2 on the low frequency response of the loop be minimal, and similar to a 2nd order loop.

- ξ = 0.707 (damping factor).
- ω i = 15750 x 2p = 98960 rad/sec (input frequency).
- τ = RC as the loop filter
- K = Ko x Ip x R/($2\pi N$) the loop gain
- K' = K x τ = $4\xi^2$ (the normalized loop gain)

$$
Ko = 70 \times 10^6 \text{ rad/V}
$$

Stability analysis with $C2 = C1/10$ and $K' = 2$ ($\xi = 0.707$) gives a minimum value of 7.5 for the ratio ωi/K. To have some margin, a reasonable value can be 15 to 20 or higher.

Selecting
$$
\omega i/K = 20
$$
 yields,
K = $\omega i/20 \approx 5000$.

Using the following items:

 $K' = 2$, τ = 2/K = 400 µs, $K = Ko \times Ip \times R/(2\pi N)$ $lp = 20 \mu A$ $N = 2000$ (average value)

vields a value of 22 kΩ for R. Using a value of 400 us for τ . C1 calculates to 18 nF, and C2 calculates to 1.8 nF.

With the above values, the loop's natural frequency (ωn), and loop bandwidth (ω3dB) can be calculated:

ωn = {(Ko/N) x lp/(2πC) }^{0.5} = 3520 rad/sec. fn = $3520/2\pi$ = 560 Hz.

 $ω3dB ≈ 2 x ωn = 1120 Hz$ (valid if ξ = 0.707).

The circuit designer should be cautioned at this point that the above calculated values are not necessarily optimum for every application. Besides the fact that several assumptions were made in the discussion, the equations cannot account for items such as the PC board layout, characteristics of the external divider, and noise from various sources. The above calculated values provide for a functional circuit, which should then be tweaked to obtain minimum jitter at the pixel clock output.

When initially adjusting the filter component values, it is advisable to maintain the same general time constant (400 μ s in this example), and the same x10 relationship between C1 and C2.

References:

⁽¹⁾ Charge–Pump Phase–Lock–Loops by Floyd M. Gardner, IEEE Transactions on Communications, Vol. com–28, no. 11, Nov. 1980.

⁽²⁾ Phaselock Techniques by Floyd M. Gardner, J. Wiley & Sons, 1979.

⁽³⁾ Phase–Locked–Loops by Roland E. Best, McGraw Hill, 1984.

⁽⁴⁾ AN–535, Phase–Locked–Loop Design Fundamentals, Motorola.

MC44011 GLOSSARY

Aspect Ratio – The ratio of the width of a TV screen to the height. In standard TVs, it is 4:3. In HDVT it will likely be 16:9.

Back Porch – The blanking time after the sync signal during which the color burst is inserted.

Blank, Pedestal – The signal level which is either at black, or slightly more negative than black ("blacker–than–black"), and is used to turn off the screen dot during retrace. Also referred to as the pedestal.

Brightness – A measure of the dc levels of the luma component. Changing brightness will change the minimum and maximum luma levels together.

Burst – The 8 to 10 cycle sine wave which is inserted in the back porch. It's frequency is the color subcarrier (3.58 MHz or 4.43 MHz), and is used as a phase reference for the color decoder.

Burst Gate – A signal identifying the time during which the burst signal occurs.

C, Chrominance – The color component of the video signal. The color is determined by the phase of the chrominance component relative to the burst signal.

Clamping – A process which establishes a fixed dc voltage level, usually during the back porch time.

Color Difference Signals – B–Y, R–Y, also designated as U and V.

Color Decoder – A circuit which separates composite video into Red, Blue, and Green, luminance, and sync signals.

Color Encoder – A circuit which combines Red, Blue, and Green, luminance, and sync signals into composite video.

Comb Filter – A multi–bandpass filter which separates the luma and chrominance components from the video signal, without sacrificing bandwidth.

Component Video, YUV – A format whereby the video information is kept as separate luma, R–Y, and B–Y signals (YUV) . U is the same as B–Y, and V is the same as R–Y.

Composite Sync – A sync signal which combines horizontal and vertical sync information. The waveform is made up of regularly spaced negative going pulses for the horizontal sync, and then half–line pulses and polarity reversal to indicate the vertical sync and retrace time.

Composite Video – The video signal which consists of sync, back porch, color burst, video information (luma and chroma), and front porch. This is the signal normally broadcast by TV stations.

Contrast – A measure of the difference between minimum and maximum luma amplitudes. Increasing contrast produces a "blacker" black and a "whiter" white.

dB – A power or voltage measurement unit, referred to another power or voltage. It is generally computed as:

10 x log (P1/P2) for power measurements, and

20 x log (V1/V2) for voltage measurements.

Field – One of the two or more equal parts into which a frame is divided in an interlaced system.

Frame – The information which makes up one complete picture. It consists of 525 lines in NTSC systems, and 625 lines in PAL systems. An interlaced system is typically composed of two fields.

Front Porch – The blanking time immediately before the sync signal.

Horizontal Sync – The negative going sync pulses at the beginning of each line. The pulses indicate to the circuit to begin sweeping the dot across the screen.

Hue – A measure of the correctness of the colors on a screen.

Interlaced System – A method of generating a picture on the screen whereby the even number lines are processed, and then the odd number lines are processed, thereby completing a full picture.

IRE – Abbreviation for International Radio Engineers, it is the amplitude unit used to define video levels. In standard NTSC signals, blank–to–white is 100 IRE units, and blank–to–sync tip is 40 IRE units. In a 1.0 Vpp signal, one IRE unit is 7.14 mV.

Luma, Y – The brightness component of the video signal. Usually abbreviated "Y", it defines the shade of gray in a black–and–white TV set. In color systems, it is composed of 0.30 red, 0.59 green and 0.11 blue.

NTSC – National Television System Committee. This committee set the color encoding standards and format for television broadcast in the United States.

PAL – *Phase Alternating Line.* A color encoding system in which the burst is alternated 90° each line to help compensate for color errors which may occur during transmission. This system is popular mainly in Europe.

Pixel – The smallest picture element, or dot, on a screen. It is determined by the design of the CRT, as well as the system bandwidth.

R–Y, B–Y – Referred to as color difference signals. These are two of the three signals of component video. When combined with Y, the full color and luminance information is available.

Retrace – The rapid movement of the blanked dot from the screen's right edge to the left edge so it can start scanning a new line. It is also the rapid movement from the lower right corner to the upper left corner during vertical blanking.

RGB – The three main colors (red, blue, green) used in the acquiring, and subsequent display of a video signal.

S–VHS – A format whereby the video information is kept as separate luma and chroma signals (Y and C).

Sandcastle – A signal which indicates the horizontal blanking time. It encompasses the front porch, sync, and back porch. Two amplitudes distinguish the front porch + sync time from the back porch.

Saturation – A measure of the intensity of the color on a screen. Also related to its purity.

Sync Separator – A circuit which will detect, and output, the sync signal from a composite video waveform.

Vertical Sync – The synchronizing signal which indicates to the circuitry to drive the dot to the upper left corner of the screen, thereby starting a new field. This signal is derived from the composite sync.

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